# Norm Estimates for Inverses of Euclidean Distance Matrices 

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#### Abstract

In this paper, we obtain a better estimate for the norm of inverses of Euclidean distance matrices of low dimensions. © 1992 Academic Press, Inc.


## 1. Introduction

We work in the Euclidean space $\mathbb{R}^{d}$, the dimension $d$ being fixed. Let $x_{1}$, $x_{2}, \ldots, x_{n}$ be $n$ distinct points (called nodes) in $R^{d}$, and let $\|\cdot\|$ be the Euclidean norm on $\mathbb{R}^{d}$. Schoenberg [8] proved that the $n \times n$ distance matrix $A=\left(\left\|x_{j}-x_{k}\right\|\right)$ has exactly 1 positive eigenvalue and $(n-1)$ negative eigenvalues. As a consequence of Schoenberg's result, the following interpolation problem is soluble: Given arbitrary data $\left\{b_{1}\right.$, $\left.b_{2}, \ldots, b_{n}\right\}$ on the node set $\left\{x_{1}, x_{2}, \ldots, x_{n}\right\}$, find a unique function $f$ in the linear span of the $n$ functions $\|x-x\|,\left\|x-x_{2}\right\|, \ldots,\left\|x-x_{n}\right\|$, such that

$$
f\left(x_{j}\right)=b_{j}, \quad(1 \leqslant j \leqslant n) .
$$

This interpolation method is a natural generalization of the piecewise linear interpolation on the real line, and is an important special case of the radial basis function interpolation. See the review papers by Dyn [3] and Powell [6].

In implementing the interpolation scheme, it is important to have an estimate for the norm of $A^{-1}$. Here we look at $A^{-1}$ as a linear operator from $\mathbb{R}^{n}$ to $\mathbb{R}^{n}$, and use the matrix norm subordinate to the Euclidean norm on $\mathbb{R}^{n}$. We also denote the matrix norm by $\|\cdot\|$, as no confusion is likely to occur. Let $\lambda_{1}, \lambda_{2}, \ldots, \lambda_{n}$ be all the eigenvalues of $A$, and let $\lambda=\min \left\{\left|\lambda_{1}\right|,\left|\lambda_{2}\right|, \ldots,\left|\lambda_{n}\right|\right\}$. Since $A$ is a real and symmetric matrix, it is elementary to see $\left\|A^{-1}\right\|=1 / \lambda$.

Ball [2] recently proved the following interesting result:
Theorem 1 (Ball). Let $x_{1}, x_{2}, \ldots, x_{n}$ be $n$ points in $\mathbb{R}^{d}$, where $d$ is an odd integer. If $\left\|x_{j}-x_{k}\right\| \geqslant \varepsilon$ for al $j \neq k$, then all the eigenvalues of $A$ have absolute values at least

$$
\begin{equation*}
\varepsilon 2^{d \cdot 1}\left(\frac{d_{d-1}^{d}}{2}\right)^{-1} \gamma_{d} \tag{1}
\end{equation*}
$$

where $\gamma_{d}$ is the distance in $C[-1,1]$ of the function $|x|$ from the space of polynomials of degree $(d-1)$ or less.

Ball [2] asserted that the estimate (1) is best possible for the case $d=1$ but is not best possible for the case $d=3$. Ball also conjectured that the estimate is not best possible for $d=5,7,9, \ldots$.

An estimate was given by Narcowich and Wartd [5] for the more general matrix

$$
A_{\alpha}=\left(\left\|x_{j}-x_{k}\right\|^{x}\right), \quad 0<x<2 .
$$

Nevertheless, when $x=1$, and $d(\geqslant 3)$ is an odd integer, their estimate is not as sharp as the one given by Ball.

Ball [2] pointed out that it is an intercsting geometric problem to determine the best possible constant, at least for $d=2$ and 3. In this paper, we provide an estimate for all dimensions $d$. Asymptotically, our estimate is weaker than Ball's; however, it yields better results for low dimensions. And our estimate is best possible for $d=1$.

## 2. The Estimate

Let $\dot{\lambda}_{1}, \lambda_{2}, \ldots, \lambda_{n}$ be the eigenvalues of the matrix $A=\left(\left\|x_{j}-x_{k}\right\|\right)$ in descending order. By Schoenberg's result mentioned in Section 1, the following inequalities are true:

$$
\dot{\lambda}_{1}>0>\lambda_{2} \geqslant \cdots \geqslant \hat{\lambda}_{n}
$$

Since the trace of $A$ is 0 , we have $\sum_{j=1}^{n} \dot{\lambda}_{j}=0$. Hence $\lambda_{1}=\sum_{j=2}^{n}\left|\hat{\lambda}_{j}\right|$. Thus $\dot{\lambda}_{2}$ is one of the cigenvalues having the smallest absolute value. By the Courant Fischer Theorem,

$$
\lambda_{2}=\min _{\operatorname{dim} V=n} \max _{1 v \in V,|v|=1} v^{T} A v \leqslant \max _{v^{T} u_{u}=0, \| v \mid-1} v^{T} A v
$$

where $u$ is the vector $(1,1, \ldots, 1)^{T}$. Formula (5) allows us to use Fourier transform techniques to estimate the quadratic form $v^{T} A v$ for $v^{T} u=0$. A similar method has been used by Narcowich and Ward [4].

Definition 2. The Fourier transform of a function $f$ in $L^{1}\left(R^{d}\right)$ is the function $\hat{f}$ defined by

$$
\hat{f}(t)=(2 \pi)^{-d / 2} \int_{R^{d}} e^{-i x t} f(x) d x
$$

The inverse Fourier transform of $f$ is the function $f$ defined $b y$

$$
\check{f}(t)=(2 \pi)^{-d / 2} \int_{R^{d}} e^{i x t} f(x) d x
$$

We also use the symbol $\mathscr{F}(f)$ to denote the Fourier transform of $f$, and the symbol $\mathscr{F}^{-1}(f)$ to denote the inverse Fourier transform of $f$. It is well known that if both $f$ and $\mathscr{F}(f)$ belong to $L^{1}\left(\mathbb{R}^{d}\right)$ then $f=\mathscr{F}-1(\mathscr{F}(f))$; see Rudin [7].

Lemma 3. Let

$$
B_{1}(x)= \begin{cases}1, & \text { if }\|x\| \leqslant 1 / 2 \\ 0, & \text { otherwise }\end{cases}
$$

Then, $\hat{B}_{1}$ is radial and

$$
\hat{B}_{1}(x)=(2 r)^{-d / 2} J_{d / 2}(r / 2), \quad r=\|x\|
$$

where $J_{v}$ is the Bessel function of the first kind.
Proof. The Lemma is trivial in the case $d=1$. So we assume that $d \geqslant 2$. Since $B_{1}$ is radial, so is $\hat{B}_{1}[9$, p. 135]. By Theorem 3.3 in [9, p. 155], we have

$$
\hat{B}_{1}(x)=r^{-(d-2) / 2} \int_{0}^{1 / 2} r^{d / 2} J_{(d-2) / 2}(r \tau) d \tau, \quad r=\|x\|
$$

A change of variable $\rho=r \tau$ in this integral leads to

$$
\begin{equation*}
\hat{B}_{1}(x)=r^{-d} \int_{0}^{r / 2} \rho^{d / 2} J_{(d-2) / 2}(\rho) d \rho, \quad r=\|x\| \tag{2}
\end{equation*}
$$

The following formula for Bessel functions can be found in Watson [10, p. 45]

$$
\frac{d}{d z}\left\{z^{v} J_{v}(z)\right\}=z^{v} J_{v-1}(z) .
$$

Hence

$$
\begin{equation*}
\left.z^{v} J_{v}(z)\right|_{a} ^{b}=\int_{a}^{b} z^{v} J_{v} \quad 1(z) d z \tag{3}
\end{equation*}
$$

Applying Eq. (3) to the integral in Eq. (2) with $v=d / 2, a=0, b=r / 2$, we get

$$
\int_{0}^{r / 2} \rho^{d ; 2} J_{(d \quad 2) ; 2}(\rho) d \rho=(r / 2)^{d / 2} J_{d ; 2}(r / 2)
$$

It follows that

$$
\hat{B}_{1}(r)=(2 r)^{d / 2} J_{d / 2}(r / 2) .
$$

Lemma 4. Let $B_{1}$ be as in Lemma 3, and let

$$
B_{2}(x)=\left(B_{1} * B_{1}\right)(x)=(2 \pi)^{d i 2} \int_{\mid y ; 1 \leqslant 1 ; 2} B_{1}(x-y) d y
$$

Then the following results are true:

1. $\quad B_{2}(0)=2^{(2-3 d) / 2} / d \Gamma(d / 2)$.
2. $\operatorname{supp}\left(B_{2}\right)=\{x:\|x\| \leqslant 1\}$.
3. $B_{2}(x)=(2 \| x \mid)^{-d} J_{d i 2}^{2}(\|x\| / 2)$. Consequently, $\hat{B}_{2} \in L^{1}\left(\mathbb{R}^{d}\right)$.

Proof. To prove Part 1, using polar coordinates, we write

$$
\begin{aligned}
B_{2}(0) & =(2 \pi)^{-d i} \int_{|: y| \leqslant 1 / 2} B_{1}(-y) d y=(2 \pi)^{-d / 2} \int_{|: y| \leqslant 1 / 2} 1 d y \\
& =(2 \pi)^{-d / 2} \cdot \frac{2 \pi^{d i 2}}{d 2^{d} \Gamma(d / 2)}=\frac{2^{(2-3 d) ; 2}}{d \Gamma(d / 2)}
\end{aligned}
$$

Part 2 is obvious.

To prove Part 3, we recall that the Fourier transform maps the convolution $B_{1} * B_{1}$ to the product $\hat{B}_{1} \cdot \hat{B}_{1}$; see Rudin [7, Theorem 7.2, p. 167]. By Lemma 3 and the definition of $B_{2}$, we have $\hat{B}_{2}(x)=(2\|x\|)^{-d} \tilde{J}_{d / 2}^{2}(\|x\| / 2)$. We observe that $\hat{B}_{2}$ is finite at the origin and that

$$
\left|\hat{B}_{2}(x)\right| \leqslant(1+\delta) \frac{4}{\pi} 2^{d}\|x\|^{-(d+1)}
$$

for $\|x\|$ large, where $\delta$ is a positive constant; see Stein and Weiss $[9$, p. 158]. It follows that $\hat{B}_{2} \in L^{1}\left(\mathbb{R}^{d}\right)$.

We remark here that since $B_{2}$ is radial we have $\mathscr{F}_{F}\left(B_{2}\right)=\mathscr{F}^{-1}\left(B_{2}\right)$. Therefore $\mathscr{F}\left(\hat{B}_{2}\right)=\mathscr{F}^{-1}\left(\hat{B}_{2}\right)=B_{2}$.

Let $S_{d-1}$ denote the unit sphere in $\mathbb{R}^{d}$. Let $\Omega_{d}$ denote the Fourier transform of the rotational invariant probability measure on $S_{d-1}$, that is,

$$
\Omega_{d}(x)=w_{d-1}^{-1} \int_{s_{d-1}} e^{i x w} d w
$$

where $d w$ denotes the usual measure on $S_{d-1}$ and $w_{d-1}$ the area of $S_{d-1}$. $\Omega_{d}$ is radial and can be expressed in terms of the Bessel function; see [8],

$$
\Omega_{d}(t)=\Gamma\left(\frac{d}{2}\right)\left(\frac{2}{t}\right)^{d / 2-1} J_{d / 2-1}(t)
$$

The following lemma concerns the integral representation of the function $\|x\|^{\alpha}(0<\alpha<2)$ by the function $\Omega_{d}$.

Lemma 5. Let $0<\alpha<2$. Then the following identity is true:

$$
\|x\|^{\alpha}=\frac{2^{1+\alpha} \Gamma((\alpha+d) / 2)}{\Gamma(-\alpha / 2) \Gamma(d / 2)} \int_{0}^{\infty} r^{-(1+\alpha)}\left[\Omega_{d}(r\|x\|)-1\right] d r .
$$

Proof. Observe that $\Omega_{d}$ is real, bounded in absolute value by 1 , and the function $\Omega_{d}(r)-1$ has a zero of order 2 at the origin, so the integrand in the above representation is absolutely integrable. Hence, using dilation invariance, we see that there exists a constant $c$, such that

$$
\|x\|^{\alpha}=c \int_{0}^{\infty} r^{-(1+\alpha)}\left[\Omega_{d}(r\|x\|)-1\right] d r .
$$

What remains in the proof is to verify that the constant is correct. To do
this, integrate both sides against the function $(2 \pi)^{-d / 2} e^{-\|x\|^{2} / 2}$ over $\mathbb{R}^{d}$. On the left hand side, we have

$$
\begin{aligned}
(2 \pi)^{-d / 2} \int_{\mathbb{R}_{d}}\|x\|^{\alpha} e^{-\|x\|^{2} / 2} d x & =\frac{w_{d-1}}{(2 \pi)^{d / 2}} \int_{0}^{\infty} t^{\alpha+d-1} e^{-t^{2} / 2} d t \\
& =\frac{2^{\alpha / 2} \Gamma((\alpha+d) / 2)}{\Gamma(d / 2)}
\end{aligned}
$$

On the right hand side, we have

$$
\begin{aligned}
(2 \pi)^{-d / 2} & \int_{\mathbb{R}_{d}} e^{-\|x\|^{2} / 2}\left\{c \int_{0}^{\infty} r^{-(1+\alpha)}\left[\Omega_{d}(r\|x\|)-1\right] d r\right\} d x \\
& =c w_{d-1}^{-1} \int_{0}^{\infty} r^{-(1+\alpha)}\left\{\int_{S_{d-1}} d w\left[(2 \pi)^{-d / 2} \int_{\mathbb{R}_{d} d} e^{i r x w} e^{-\|x\|^{2} / 2} d x\right]-1\right\} d r \\
& =c \int_{0}^{\infty} r^{-(1+\alpha)}\left(e^{-r^{2} / 2}-1\right) d r \\
& =c \int_{0}^{\infty}\left(e^{-r^{2} / 2}-1\right) d\left(-\frac{r^{-\alpha}}{\alpha}\right) \\
& =-\frac{c}{\alpha} \int_{0}^{\infty} r^{1-\alpha} e^{-r^{2} / 2} d r \\
& =-\frac{c \Gamma(1-\alpha / 2)}{\alpha 2^{\alpha / 2}}
\end{aligned}
$$

Here we used the fact that the function $e^{-\|x\|^{2} / 2}$ is invariant under the Fourier transform. Thus we have

$$
c=\frac{2^{1+\alpha} \Gamma((\alpha+d) / 2)}{\Gamma(-\alpha / 2) \Gamma(d / 2)}
$$

Theorem 6. Let $x_{1}, x_{2}, \ldots, x_{n} \in \mathbb{R}^{d}$ with $\min _{j \neq k}\left\|x_{j}-x_{k}\right\|=\varepsilon>0$. Then all the eigenvalues of the matrix $A=\left(\left\|x_{j}-x_{k}\right\|\right)$ have absolute values at least

$$
\frac{\varepsilon \Gamma((d+1) / 2)}{\sqrt{\pi} d \Lambda_{d} \Gamma(d / 2)}
$$

where $A_{d}=\sup _{r \geqslant 0}\left[r J_{d / 2}^{2}(r)\right]$.
Proof. We first explain that we may assume $\varepsilon=1$ without loss of generality. Indeed, let $x_{j}^{\prime}=\varepsilon^{-1} x_{j}$. We then have

$$
\min _{j \neq k}\left\|x_{j}^{\prime}-x_{k}^{\prime}\right\|=\min _{j \neq k} \varepsilon^{-1}\left\|x_{j}-x_{k}\right\|=1 .
$$

If $\lambda_{1}, \ldots, \lambda_{n}$ are the eigenvalues of the matrix $A^{\prime}=\left(\left\|x_{j}^{\prime}-x_{k}^{\prime}\right\|\right)$, then $\varepsilon \lambda_{1}, \ldots, \varepsilon \lambda_{n}$ are the eigenvalues of the matrix $A=\left(\left\|x_{j}-x_{k}\right\|\right)$.

Using Lemma 5 with $\alpha=1$, we have

$$
\|x\|=\Delta_{d} \int_{0}^{\infty} r^{-2}\left[\Omega_{d}(r\|x\|)-1\right] d r,
$$

where $\Delta_{d}:=-2 \Gamma((d+1) / 2) / \Gamma(1 / 2)$.
Let $v \in \mathbb{R}^{n}, v^{T} u=0$. We have

$$
\begin{aligned}
v^{T} A v & =A_{d} \int_{0}^{\infty} r^{-2} \sum_{j, k=1}^{n} v_{j} v_{k} \Omega_{d}\left(r\left\|x_{j}-x_{k}\right\|\right) d r \\
& =A_{d} w_{d-1}^{-1} \int_{0}^{\infty} r^{-2}\left[\int_{S_{d-1}} \sum_{j, k=1}^{n} v_{j} v_{k} e^{i r\left(x_{j}-x_{k}\right) w} d w\right] d r \\
& =\Delta_{d} w_{d-1}^{-1} \int_{0}^{\infty} r^{-2}\left[\int_{S_{d-1}}\left|\sum_{j=1}^{n} v_{j} e^{i x_{j} r w}\right|^{2} d w\right] d r \\
& =A_{d} w_{d-1}^{-1} \int_{\mathbb{R}^{d}}\left|\sum_{j=1}^{n} v_{j} e^{i x_{j} r w}\right|^{2}\|t\|^{-(d+1)} d t .
\end{aligned}
$$

For all $r \geqslant 0$, by the definition of the number $\Lambda_{d}$, we have $r J_{d / 2}^{2}(r) \leqslant \Lambda_{d}$. Consequently, $r J_{d / 2}^{2}(r / 2) \leqslant 2 \Lambda_{d}$. Hence

$$
\frac{r J_{d / 2}^{2}(r / 2)}{r^{d+1}} \leqslant \frac{2 A_{d}}{r^{d+1}} \quad(r>0) .
$$

Since $\Delta_{d}$ is a negative constant, it follows that

$$
\begin{aligned}
v^{T} A v & =\Delta_{d}\left(2 w_{d-1} A_{d}\right)^{-1} \int_{\mathbb{R}^{d}}\left|\sum_{j=1}^{n} v_{j} e^{i x_{j} t}\right|^{2} \frac{2 A_{d}}{\|t\|^{d+1}} d t \\
& \leqslant A_{d}\left(2 w_{d-1} A_{d}\right)^{-1} \int_{\mathbb{R}^{d}}\left|\sum_{j=1}^{n} v_{j} e^{i x_{i} t}\right|^{2} \frac{\|t\| J_{d / 2}^{2}(\|t\| / 2)}{\|t\|^{d+k}} d t \\
& =2^{d} A_{d}\left(2 w_{d-1} A_{d}\right)^{-1} \int_{\mathbb{R}^{d}}\left[\sum_{j, k=1}^{n} v_{j} v_{k} e^{i\left(x_{j}-x_{k}\right) t}\right] \hat{B}_{2}(\|t\|) d t,
\end{aligned}
$$

where the function $B_{2}$ is defined as in Lemma 4.
By Lemma 4 and the remark following it, we have

$$
(2 \pi)^{-d / 2} \int_{\mathbb{R}^{d}} e^{i\left(x_{j}-x_{k}\right) t} \hat{B}_{2}(\|t\|) d t=B_{2}\left(\left\|x_{j}-x_{k}\right\|\right) .
$$

## Therefore

$$
v^{T} A v \leqslant 2^{d}(2 \pi)^{d / 2} \Delta_{d}\left(2 w_{d-1} \Lambda_{d}\right)^{-1} \sum_{j, k=1}^{n} v_{j} v_{k} B_{2}\left(\left\|x_{j}-x_{k}\right\|\right) .
$$

Finally, because $\min _{j \neq k}\left\|x_{j}-x_{k}\right\|=1$, and $\sup \left(B_{2}\right)=\{x:\|x\| \leqslant 1\}$, we obtain

$$
\begin{aligned}
v^{T} A v & \leqslant\left[2^{d}(2 \pi)^{d / 2} \Delta_{d}\left(2 w_{d-1} \Lambda_{d}\right)^{-1} B_{2}(0)\right] \sum_{j=1}^{n} v_{j}^{2} \\
& =-\frac{\Gamma((d+1) / 2)}{\sqrt{\pi} d \Lambda_{d} \Gamma(d / 2)} \sum_{j=1}^{n} v_{j}^{2}
\end{aligned}
$$

According to the remarks at the beginning of this section, we see that the proof is completed by an application of the Courant-Fischer Theorem.

The estimate given by Theorem 6 holds for all dimension $d$. When $d=1$, we have (see [10, p. 54])

$$
J_{1 / 2}(z)=\sqrt{\frac{2}{\pi z}} \sin z
$$

Thus $\Lambda_{1}=2 / \pi$ and estimate (3) gives $\varepsilon / 2$. The author was informed by B. J. C. Baxter that he and M. Powell had verified that the estimate $\varepsilon / 2$ is best possible for the case $d=1$. When $d=3$, we have (see [10, p. 54])

$$
J_{3 / 2}(z)=\sqrt{\frac{2}{\pi z}}\left(\frac{\sin z}{z}-\cos z\right)
$$

Numerical experiment suggests that $\Lambda_{3}<2.4 / \pi$, and estimate (3) gives a bound which is greater than $\varepsilon / 3.6$, and which is better than the one given by Theorem 1 where the bound is given to be $\varepsilon / 4$. And this confirms Ball's assertion that $\varepsilon / 4$ is not best possible. However, according to Formula 9.3.5 in [1], $J_{m}(m)$ is of the order $m^{-1 / 3}$ so that our estimate is of the order $\varepsilon d^{-5 / 6}$ asymptotically, thus, our estimate is weaker than the one given by Theorem 1 for $d$ sufficiently large.

It would be interesting to determine if the estimate given by Theorem 6 is best possible for $d=2,3$. The problem seems to be related to sphere packings in $\mathbb{R}^{d}$. We caution that the sphere packing problem in $\mathbb{R}^{d}$ has not been settled for $d \geqslant 3$.

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