JOURNAL OF APPROXIMATION THEORY 70, 339-347 (1992)

# Norm Estimates for Inverses of Euclidean Distance Matrices

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Communicated by Nira Dyn

Received August 20, 1990; revised June 2, 1991

In this paper, we obtain a better estimate for the norm of inverses of Euclidean distance matrices of low dimensions. © 1992 Academic Press, Inc.

### 1. INTRODUCTION

We work in the Euclidean space  $\mathbb{R}^d$ , the dimension *d* being fixed. Let  $x_1$ ,  $x_2, ..., x_n$  be *n* distinct points (called nodes) in  $\mathbb{R}^d$ , and let  $\|\cdot\|$  be the Euclidean norm on  $\mathbb{R}^d$ . Schoenberg [8] proved that the  $n \times n$  distance matrix  $A = (\|x_j - x_k\|)$  has exactly 1 positive eigenvalue and (n-1) negative eigenvalues. As a consequence of Schoenberg's result, the following interpolation problem is soluble: Given arbitrary data  $\{b_1, b_2, ..., b_n\}$  on the node set  $\{x_1, x_2, ..., x_n\}$ , find a unique function *f* in the linear span of the *n* functions  $\|x - x\|$ ,  $\|x - x_2\|$ , ...,  $\|x - x_n\|$ , such that

$$f(x_i) = b_i, \qquad (1 \le j \le n).$$

This interpolation method is a natural generalization of the piecewise linear interpolation on the real line, and is an important special case of the radial basis function interpolation. See the review papers by Dyn [3] and Powell [6].

In implementing the interpolation scheme, it is important to have an estimate for the norm of  $A^{-1}$ . Here we look at  $A^{-1}$  as a linear operator from  $\mathbb{R}^n$  to  $\mathbb{R}^n$ , and use the matrix norm subordinate to the Euclidean norm on  $\mathbb{R}^n$ . We also denote the matrix norm by  $\|\cdot\|$ , as no confusion is likely to occur. Let  $\lambda_1, \lambda_2, ..., \lambda_n$  be all the eigenvalues of A, and let  $\lambda = \min\{|\lambda_1|, |\lambda_2|, ..., |\lambda_n|\}$ . Since A is a real and symmetric matrix, it is elementary to see  $\|A^{-1}\| = 1/\lambda$ .

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Ball [2] recently proved the following interesting result:

**THEOREM 1** (Ball). Let  $x_1, x_2, ..., x_n$  be n points in  $\mathbb{R}^d$ , where d is an odd integer. If  $||x_j - x_k|| \ge \varepsilon$  for al  $j \ne k$ , then all the eigenvalues of A have absolute values at least

$$\varepsilon 2^{d-1} \left(\frac{\frac{d-1}{d-1}}{2}\right)^{-1} \gamma_d,\tag{1}$$

where  $\gamma_d$  is the distance in C[-1, 1] of the function |x| from the space of polynomials of degree (d-1) or less.

Ball [2] asserted that the estimate (1) is best possible for the case d = 1 but is not best possible for the case d = 3. Ball also conjectured that the estimate is not best possible for d = 5, 7, 9, ...

An estimate was given by Narcowich and Wartd [5] for the more general matrix

$$A_{\alpha} = (||x_{i} - x_{k}||^{\alpha}), \quad 0 < \alpha < 2.$$

Nevertheless, when  $\alpha = 1$ , and  $d \ (\geq 3)$  is an odd integer, their estimate is not as sharp as the one given by Ball.

Ball [2] pointed out that it is an interesting geometric problem to determine the best possible constant, at least for d=2 and 3. In this paper, we provide an estimate for all dimensions d. Asymptotically, our estimate is weaker than Ball's; however, it yields better results for low dimensions. And our estimate is best possible for d=1.

# 2. The Estimate

Let  $\lambda_1$ ,  $\lambda_2$ , ...,  $\lambda_n$  be the eigenvalues of the matrix  $A = (||x_j - x_k||)$  in descending order. By Schoenberg's result mentioned in Section 1, the following inequalities are true:

$$\lambda_1 > 0 > \lambda_2 \ge \cdots \ge \lambda_n.$$

Since the trace of A is 0, we have  $\sum_{j=1}^{n} \lambda_j = 0$ . Hence  $\lambda_1 = \sum_{j=2}^{n} |\lambda_j|$ . Thus  $\lambda_2$  is one of the eigenvalues having the smallest absolute value. By the Courant Fischer Theorem,

$$\lambda_2 = \min_{\dim V = n} \max_{1 \quad v \in V, \ \|v\| = 1} v^T A v \leq \max_{v^T u = 0, \ \|v\| = 1} v^T A v,$$

where u is the vector  $(1, 1, ..., 1)^T$ . Formula (5) allows us to use Fourier transform techniques to estimate the quadratic form  $v^T A v$  for  $v^T u = 0$ . A similar method has been used by Narcowich and Ward [4].

**DEFINITION 2.** The Fourier transform of a function f in  $L^1(\mathbb{R}^d)$  is the function  $\hat{f}$  defined by

$$\hat{f}(t) = (2\pi)^{-d/2} \int_{\mathbb{R}^d} e^{-ixt} f(x) \, dx$$

The inverse Fourier transform of f is the function  $\check{f}$  defined by

$$\check{f}(t) = (2\pi)^{-d/2} \int_{R^d} e^{ixt} f(x) \, dx.$$

We also use the symbol  $\mathscr{F}(f)$  to denote the Fourier transform of f, and the symbol  $\mathscr{F}^{-1}(f)$  to denote the inverse Fourier transform of f. It is well known that if both f and  $\mathscr{F}(f)$  belong to  $L^1(\mathbb{R}^d)$  then  $f = \mathscr{F}^{-1}(\mathscr{F}(f))$ ; see Rudin [7].

LEMMA 3. Let

$$B_1(x) = \begin{cases} 1, & \text{if } ||x|| \le 1/2\\ 0, & \text{otherwise.} \end{cases}$$

Then,  $\hat{B}_1$  is radial and

$$\hat{B}_1(x) = (2r)^{-d/2} J_{d/2}(r/2), \qquad r = ||x||,$$

where  $J_{v}$  is the Bessel function of the first kind.

*Proof.* The Lemma is trivial in the case d = 1. So we assume that  $d \ge 2$ . Since  $B_1$  is radial, so is  $\hat{B}_1$  [9, p. 135]. By Theorem 3.3 in [9, p. 155], we have

$$\hat{B}_1(x) = r^{-(d-2)/2} \int_0^{1/2} r^{d/2} J_{(d-2)/2}(r\tau) \, d\tau, \qquad r = \|x\|.$$

A change of variable  $\rho = r\tau$  in this integral leads to

$$\hat{B}_1(x) = r^{-d} \int_0^{r/2} \rho^{d/2} J_{(d-2)/2}(\rho) \, d\rho, \qquad r = \|x\|.$$
(2)

The following formula for Bessel functions can be found in Watson [10, p. 45]

$$\frac{d}{dz}\left\{z^{\nu}J_{\nu}(z)\right\}=z^{\nu}J_{\nu-1}(z).$$

Hence

$$z^{\nu}J_{\nu}(z)\mid_{a}^{b} = \int_{a}^{b} z^{\nu}J_{\nu-1}(z) dz.$$
(3)

Applying Eq. (3) to the integral in Eq. (2) with v = d/2, a = 0, b = r/2, we get

$$\int_0^{r/2} \rho^{d/2} J_{(d-2)/2}(\rho) \, d\rho = (r/2)^{d/2} \, J_{d/2}(r/2).$$

It follows that

$$\hat{B}_1(r) = (2r)^{-d/2} J_{d/2}(r/2).$$

LEMMA 4. Let  $B_1$  be as in Lemma 3, and let

$$B_2(x) = (B_1 * B_1)(x) = (2\pi)^{-d/2} \int_{\|y\| \le 1/2} B_1(x-y) \, dy.$$

Then the following results are true:

1. 
$$B_2(0) = 2^{(2-3d)/2}/d\Gamma(d/2).$$

2. 
$$\operatorname{supp}(B_2) = \{x : ||x|| \le 1\}.$$

3.  $B_2(x) = (2 ||x|)^{-d} J_{d/2}^2(||x||/2)$ . Consequently,  $\hat{B}_2 \in L^1(\mathbb{R}^d)$ .

Proof. To prove Part 1, using polar coordinates, we write

$$B_2(0) = (2\pi)^{-d/2} \int_{\|y\| \le 1/2} B_1(-y) \, dy = (2\pi)^{-d/2} \int_{\|y\| \le 1/2} 1 \, dy$$
$$= (2\pi)^{-d/2} \cdot \frac{2\pi^{d/2}}{d2^d \Gamma(d/2)} = \frac{2^{(2-3d)/2}}{d\Gamma(d/2)}.$$

Part 2 is obvious.

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To prove Part 3, we recall that the Fourier transform maps the convolution  $B_1 * B_1$  to the product  $\hat{B}_1 \cdot \hat{B}_1$ ; see Rudin [7, Theorem 7.2, p. 167]. By Lemma 3 and the definition of  $B_2$ , we have  $\hat{B}_2(x) = (2 ||x||)^{-d} J_{d/2}^2(||x||/2)$ . We observe that  $\hat{B}_2$  is finite at the origin and that

$$|\hat{B}_2(x)| \leq (1+\delta) \frac{4}{\pi} 2^d ||x||^{-(d+1)}$$

for ||x|| large, where  $\delta$  is a positive constant; see Stein and Weiss [9, p. 158]. It follows that  $\hat{B}_2 \in L^1(\mathbb{R}^d)$ .

We remark here that since  $B_2$  is radial we have  $\mathscr{F}(B_2) = \mathscr{F}^{-1}(B_2)$ . Therefore  $\mathscr{F}(\hat{B}_2) = \mathscr{F}^{-1}(\hat{B}_2) = B_2$ .

Let  $S_{d-1}$  denote the unit sphere in  $\mathbb{R}^d$ . Let  $\Omega_d$  denote the Fourier transform of the rotational invariant probability measure on  $S_{d-1}$ , that is,

$$\Omega_d(x) = w_{d-1}^{-1} \int_{s_{d-1}} e^{ixw} \, dw,$$

where dw denotes the usual measure on  $S_{d-1}$  and  $w_{d-1}$  the area of  $S_{d-1}$ .  $\Omega_d$  is radial and can be expressed in terms of the Bessel function; see [8],

$$\Omega_d(t) = \Gamma\left(\frac{d}{2}\right) \left(\frac{2}{t}\right)^{d/2 - 1} J_{d/2 - 1}(t).$$

The following lemma concerns the integral representation of the function  $||x||^{\alpha}$  (0 <  $\alpha$  < 2) by the function  $\Omega_d$ .

LEMMA 5. Let  $0 < \alpha < 2$ . Then the following identity is true:

$$\|x\|^{\alpha} = \frac{2^{1+\alpha} \Gamma((\alpha+d)/2)}{\Gamma(-\alpha/2) \Gamma(d/2)} \int_{0}^{\infty} r^{-(1+\alpha)} [\Omega_{d}(r \|x\|) - 1] dr.$$

*Proof.* Observe that  $\Omega_d$  is real, bounded in absolute value by 1, and the function  $\Omega_d(r) - 1$  has a zero of order 2 at the origin, so the integrand in the above representation is absolutely integrable. Hence, using dilation invariance, we see that there exists a constant c, such that

$$\|x\|^{\alpha} = c \int_{0}^{\infty} r^{-(1+\alpha)} [\Omega_{d}(r \|x\|) - 1] dr.$$

What remains in the proof is to verify that the constant is correct. To do

this, integrate both sides against the function  $(2\pi)^{-d/2} e^{-\|x\|^2/2}$  over  $\mathbb{R}^d$ . On the left hand side, we have

$$(2\pi)^{-d/2} \int_{\mathbb{R}_d} \|x\|^{\alpha} e^{-\|x\|^{2/2}} dx = \frac{w_{d-1}}{(2\pi)^{d/2}} \int_0^\infty t^{\alpha+d-1} e^{-t^{2/2}} dt$$
$$= \frac{2^{\alpha/2} \Gamma((\alpha+d)/2)}{\Gamma(d/2)}.$$

On the right hand side, we have

$$(2\pi)^{-d/2} \int_{\mathbb{R}_d} e^{-\|x\|^{2/2}} \left\{ c \int_0^\infty r^{-(1+\alpha)} [\Omega_d(r \|x\|) - 1] dr \right\} dx$$
  

$$= c w_{d-1}^{-1} \int_0^\infty r^{-(1+\alpha)} \left\{ \int_{S_{d-1}} dw \left[ (2\pi)^{-d/2} \int_{\mathbb{R}^d} e^{irxw} e^{-\|x\|^{2/2}} dx \right] - 1 \right\} dr$$
  

$$= c \int_0^\infty r^{-(1+\alpha)} (e^{-r^{2/2}} - 1) dr$$
  

$$= c \int_0^\infty (e^{-r^{2/2}} - 1) d \left( -\frac{r^{-\alpha}}{\alpha} \right)$$
  

$$= -\frac{c}{\alpha} \int_0^\infty r^{1-\alpha} e^{-r^{2/2}} dr$$
  

$$= -\frac{c\Gamma(1-\alpha/2)}{\alpha 2^{\alpha/2}}.$$

Here we used the fact that the function  $e^{-\|x\|^2/2}$  is invariant under the Fourier transform. Thus we have

$$c = \frac{2^{1+\alpha} \Gamma((\alpha+d)/2)}{\Gamma(-\alpha/2) \Gamma(d/2)}.$$

THEOREM 6. Let  $x_1, x_2, ..., x_n \in \mathbb{R}^d$  with  $\min_{j \neq k} ||x_j - x_k|| = \varepsilon > 0$ . Then all the eigenvalues of the matrix  $A = (||x_j - x_k||)$  have absolute values at least

$$\frac{\varepsilon\Gamma((d+1)/2)}{\sqrt{\pi}\,d\Lambda_d\Gamma(d/2)},$$

where  $\Lambda_d = \sup_{r \ge 0} [r J_{d/2}^2(r)].$ 

*Proof.* We first explain that we may assume  $\varepsilon = 1$  without loss of generality. Indeed, let  $x'_i = \varepsilon^{-1}x_i$ . We then have

$$\min_{j \neq k} \|x_j' - x_k'\| = \min_{j \neq k} \varepsilon^{-1} \|x_j - x_k\| = 1.$$

If  $\lambda_1, ..., \lambda_n$  are the eigenvalues of the matrix  $A' = (||x_j' - x_k'||)$ , then  $\varepsilon \lambda_1, ..., \varepsilon \lambda_n$  are the eigenvalues of the matrix  $A = (||x_j - x_k||)$ .

Using Lemma 5 with  $\alpha = 1$ , we have

$$||x|| = \Delta_d \int_0^\infty r^{-2} [\Omega_d(r ||x||) - 1] dr,$$

where  $\Delta_d := -2\Gamma((d+1)/2)/\Gamma(1/2)$ . Let  $v \in \mathbb{R}^n$ ,  $v^T u = 0$ . We have

$$v^{T}Av = \Delta_{d} \int_{0}^{\infty} r^{-2} \sum_{j,k=1}^{n} v_{j}v_{k}\Omega_{d}(r ||x_{j} - x_{k}||) dr$$
  
=  $\Delta_{d}w_{d-1}^{-1} \int_{0}^{\infty} r^{-2} \left[ \int_{S_{d-1}} \sum_{j,k=1}^{n} v_{j}v_{k}e^{ir(x_{j} - x_{k})w} dw \right] dr$   
=  $\Delta_{d}w_{d-1}^{-1} \int_{0}^{\infty} r^{-2} \left[ \int_{S_{d-1}} \left| \sum_{j=1}^{n} v_{j}e^{ix_{j}rw} \right|^{2} dw \right] dr$   
=  $\Delta_{d}w_{d-1}^{-1} \int_{\mathbb{R}^{d}} \left| \sum_{j=1}^{n} v_{j}e^{ix_{j}rw} \right|^{2} ||t||^{-(d+1)} dt.$ 

For all  $r \ge 0$ , by the definition of the number  $\Lambda_d$ , we have  $rJ_{d/2}^2(r) \le \Lambda_d$ . Consequently,  $rJ_{d/2}^2(r/2) \le 2\Lambda_d$ . Hence

$$\frac{rJ_{d/2}^2(r/2)}{r^{d+1}} \leqslant \frac{2\Lambda_d}{r^{d+1}} \qquad (r > 0).$$

Since  $\Delta_d$  is a negative constant, it follows that

$$v^{T}Av = \Delta_{d}(2w_{d-1}\Lambda_{d})^{-1} \int_{\mathbb{R}^{d}} \left| \sum_{j=1}^{n} v_{j}e^{ix_{j}t} \right|^{2} \frac{2\Lambda_{d}}{\|t\|^{d+1}} dt$$
  
$$\leq \Delta_{d}(2w_{d-1}\Lambda_{d})^{-1} \int_{\mathbb{R}^{d}} \left| \sum_{j=1}^{n} v_{j}e^{ix_{j}t} \right|^{2} \frac{\|t\| J_{d/2}^{2}(\|t\|/2)}{\|t\|^{d+k}} dt$$
  
$$= 2^{d}\Delta_{d}(2w_{d-1}\Lambda_{d})^{-1} \int_{\mathbb{R}^{d}} \left[ \sum_{j,k=1}^{n} v_{j}v_{k}e^{i(x_{j}-x_{k})t} \right] \hat{B}_{2}(\|t\|) dt,$$

where the function  $B_2$  is defined as in Lemma 4.

By Lemma 4 and the remark following it, we have

$$(2\pi)^{-d/2} \int_{\mathbb{R}^d} e^{i(x_j - x_k)t} \hat{B}_2(||t||) dt = B_2(||x_j - x_k||).$$

Therefore

$$v^{T}Av \leq 2^{d}(2\pi)^{d/2} \Delta_{d}(2w_{d-1}\Lambda_{d})^{-1} \sum_{j,k=1}^{n} v_{j}v_{k}B_{2}(||x_{j}-x_{k}||)$$

Finally, because  $\min_{j \neq k} ||x_j - x_k|| = 1$ , and  $\sup(B_2) = \{x : ||x|| \le 1\}$ , we obtain

$$v^{T}Av \leq \left[2^{d}(2\pi)^{d/2} \Delta_{d}(2w_{d-1}\Lambda_{d})^{-1} B_{2}(0)\right] \sum_{j=1}^{n} v_{j}^{2}.$$
$$= -\frac{\Gamma((d+1)/2)}{\sqrt{\pi} d\Lambda_{d}\Gamma(d/2)} \sum_{j=1}^{n} v_{j}^{2}.$$

According to the remarks at the beginning of this section, we see that the proof is completed by an application of the Courant–Fischer Theorem.

The estimate given by Theorem 6 holds for all dimension d. When d = 1, we have (see [10, p. 54])

$$J_{1/2}(z) = \sqrt{\frac{2}{\pi z}} \sin z.$$

Thus  $A_1 = 2/\pi$  and estimate (3) gives  $\varepsilon/2$ . The author was informed by B. J. C. Baxter that he and M. Powell had verified that the estimate  $\varepsilon/2$  is best possible for the case d = 1. When d = 3, we have (see [10, p. 54])

$$J_{3/2}(z) = \sqrt{\frac{2}{\pi z}} \left( \frac{\sin z}{z} - \cos z \right).$$

Numerical experiment suggests that  $\Lambda_3 < 2.4/\pi$ , and estimate (3) gives a bound which is greater than  $\varepsilon/3.6$ , and which is better than the one given by Theorem 1 where the bound is given to be  $\varepsilon/4$ . And this confirms Ball's assertion that  $\varepsilon/4$  is not best possible. However, according to Formula 9.3.5 in [1],  $J_m(m)$  is of the order  $m^{-1/3}$  so that our estimate is of the order  $\varepsilon d^{-5/6}$  asymptotically, thus, our estimate is weaker than the one given by Theorem 1 for d sufficiently large.

It would be interesting to determine if the estimate given by Theorem 6 is best possible for d=2, 3. The problem seems to be related to sphere packings in  $\mathbb{R}^d$ . We caution that the sphere packing problem in  $\mathbb{R}^d$  has not been settled for  $d \ge 3$ .

#### ACKNOWLEDGMENTS

This paper is part of a dissertation written under the supervision of Professor E. W. Cheney. The author thanks Professors E. W. Cheney and W. Beckner for valuable advice. Also, the author thanks the referees for their insightful suggestions.

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